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APRIL 27 2014 **NEWSLETTER WEEK 14**

"All in the Timing"
by David Ives

a One-Act Play
starring a Robot

and How We Did It

May 1, 2014
8PM
Helen Wayne Rauh Studio Theatre

Starring HERB the Robot Butler and Olivia Brown
Directed by Sam French

This production is a collaboration of the Personal Robotics Lab, the School of Drama, and the Entertainment Technology Center.

personalrobotics.ri.cmu.edu/drama

Final Performance Week!

After having a successful soft opening in which we showcase the capabilities and features of our interface, we have ahead of us the Final Performance.

In preparation for the Final Performance, the past week we did some optimizations on the interface and we had several

rehearsal sessions in the Personal Robotics Lab. We were able to share and discuss the the director Sam French about our tool and how we are going to show the features of our interface in the “behind the scenes” part of the performance.

Most likely we would have the Director giving several instructions and one operator tweaking and fine tuning HERB’s expressions based on those instructions.

This week we also worked on cleaning up all our documentation and references so we can start preparing for the Finals week.

Rehearsals

This week we continue with the rehearsals and testing.

The director Sam French and the team decided on which lines of the play are going to be interpreted and explained in the “behind the curtains” part of the play.

We also had the opportunity of discussing some operational details of the performance

Playtest

We continued with the design of a playtest that would be based on both, the recorded footage of the robot and some simulator animations showcasing the different levels of openness and intensity.

The idea in this moment is to create a simple but yet, rich questionnaire that would let

and how are we going to showcase all the internal animation and direction process.

In the following link you can find the lines that would be played for the “behind the curtains”:

<http://tinyurl.com/n5yhol7>

us ask the participants questions that will help us to prove the effectiveness of the parametrization and the resulting animations, as well as the response of an audience towards the footage of HERB executing certain trajectories.

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